

# Lecture 1: KLEIN GEOMETRIES

## §1. Main definition

$(X:G)$  is a set with a transformation group acting on it if  $X$  is a set,  $\emptyset \neq G \subset \text{Bij } X$  ( $g: X \rightarrow X, g: x \mapsto xg$ ) such that

- (i)  $g \in G \Rightarrow g^{-1} \in G$
- (ii)  $g_1, g_2 \in G \Rightarrow g_1 * g_2 \in G$
- (iii)  $x(g_1 * g_2) = (xg_1)g_2$

Remarks •  $\text{id} \in G$  (Proof:  $\emptyset \neq G \Rightarrow \exists g \in G \xrightarrow{(i)} g^{-1} \in G \xrightarrow{(ii)} G \ni gg^{-1} = \text{id}$ .)

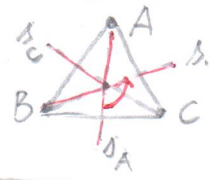
•  $G$  satisfies the axioms for groups (ома таа, ктo знае!)

Short terminology:  $(X:G)$  is a Klein geometry

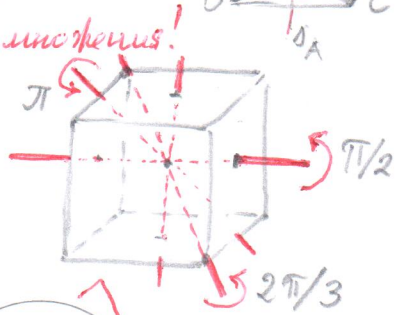
## §2 Examples

(0) Euclidean plane geometry:  $X = \mathbb{R}^2 = \{(x,y) \mid x,y \in \mathbb{R}\}, G = \text{Ismttr } \mathbb{R}^2$   
 Би дојдеши знае о сродни Ismttr: н.перенос, поворот, скользящая ам.

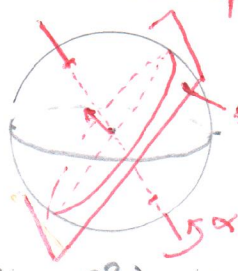
(1) Symmetries of  $\Delta$ :  $X = \Delta, G = \text{Ismttr}(\Delta) \equiv \text{Sym } \Delta$   
 $\text{Sym}(\Delta) = \{r_0, r_1, r_2, s_A, s_B, s_C\}$   $s_A * r_1 \neq r_1 * s_A$   
 $A \xrightarrow{s_A} A \xrightarrow{r_1} B \quad A \xrightarrow{r_1} B \xrightarrow{s_A} C$  *таблицу умножения!*



(2) Rotations of  $\mathbb{I}^3$ :  $(\mathbb{I}^3: \text{Rot } \mathbb{I}^3)$   
 $\text{id}, 3 \times \{\pi/2, \pi, 3\pi/2\} + 6 \times \{\pi\} + 4 \times \{\frac{2\pi}{3}, \frac{4\pi}{3}\}$   
 $\text{ord}(\text{Rot } \mathbb{I}^3) = 1 + 9 + 6 + 8 = 24$   
 Најдуже  $\text{ord}(\text{Sym } \mathbb{I}^3)$

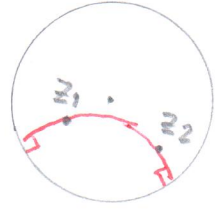


(3) Spherical geometry:  $(S^3: \text{Sym } S^3)$   
 $\text{Sym } S^3 = \{\{\theta_\alpha\}, \{\pi_\theta\}\}$   $\text{ord } \text{Sym } S^3 = \infty$   
 $\text{Rot } S^3 = 50^3$   
 $\text{Sym } S^3 = 0^3$



(4) Riemann's elliptic geometry:  $X = \{(x,-x) \mid x \in S^2\}, G = 0^3$   
 точка  $\equiv$  пара точек (!) *прямые!*

(5) Lobachevsky's hyperbolic geometry  $X = \{z \in \mathbb{C} \mid |z| < 1\}$ ,  
 $G = \text{Ismttr}_d$ , where  $d(z_1, z_2) = \ln \frac{|1 - z_1 \bar{z}_2| + |z_1 - z_2|}{|1 - z_1 \bar{z}_2| - |z_1 - z_2|}$   
*три прямые! прямые!*



(6) Same as (3), (4), (5) but in dimension three

Remark • any "geometry" is a Klein geometry, but  
 • a Klein geometry is not necessarily a "geometry"

### §3 Abstract groups

- A set  $G$  with a binary operation  $*$  is a group, if
- $\exists e \in G$  s.t.  $e * g = g * e = g \quad \forall g$  (neutral element)
  - $\forall g \in G \exists ! g^{-1} \in G$  s.t.  $g * g^{-1} = g^{-1} * g = e$  (inverse element)
  - $*$  is associative, i.e.  $(g * h) * k = g * (h * k) \quad \forall g, h, k \in G$

*Обычно знак  $*$  опускается*

A group is Abelian (=commutative) if  $gh = hg \quad \forall g, h \in G$

Proposition If  $(X: G)$  is a Klein geometry, then  $G$  is a group.

Proof. Let  $*$  be composition (which is associative) and  $e := id$ .

Expls: see 2.0-2.5 and exercise class.

Defn Let  $G, H$  be groups, let  $h: G \rightarrow H$  be a map s.t.  $h(gg') = h(g)h(g')$   
homomorphism, mono, epi, iso

### §4 Morphisms of geometries

*Геометрии по Клейну образуют категорию ...*

Definitions A morphism  $\mu: (X: G) \rightarrow (Y: H)$  is a pair of maps  $\varphi: X \rightarrow Y, \delta: G \rightarrow H$  s.t.  $\delta$  is a homomorphism and the diagram is commutative for all  $g \in G$ , i.e.

$$\varphi(xg) = (\varphi(x))(\delta(g)) \quad \forall g \in G \quad \forall x \in X$$

$$\begin{array}{ccc} X & \xrightarrow{\varphi} & Y \\ g \downarrow & & \downarrow \delta(g) \\ X & \xrightarrow{\varphi} & Y \end{array}$$

Remark "morphism"  $\sim$  "equivariant map"

- If  $\varphi$  is a bijection and  $\delta$  is an isomorphism, then  $\mu$  is called an isomorphism of geometries
- If  $\varphi$  is injective and  $\delta$  is a monomorphism, then  $\mu$  is called an injective morphism and we say that  $(X, G)$  is a subgeometry of  $(X', G')$ .
- If  $\varphi$  is surjective ...

Examples. (i)  $(\square; \text{Sym } \square) \hookrightarrow (\square; \text{Sym}(\square))$

(ii)  $(\mathbb{R}^2; \text{Isom}_d \mathbb{R}^2) \xrightarrow{\cong} (\mathbb{R}^2; \text{Isom}_{2d} \mathbb{R}^2)$

(iii)  $(S^2; O^3) \rightarrow (S^2/\text{Ant}, O^3)$  surjective morphism

(iv)  $(\Delta; \text{Rot } \Delta) \hookrightarrow \mathbb{I}^3, (\text{Rot } \mathbb{I}^3)$